Introduction to homotopy theory

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Topology studies topological spaces and continuous maps. There is a lot of invariants (properties) that allow to differ one topological space from another (compactness, connectedness, metrizability, etc.)

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Advantage of homotopy classifications:

• number of objects becomes discrete

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- number of objects becomes discrete
- the set of objects often carries an algebraic structure (groups, rings, semigroups, etc)
- applications: almost always discrete ("quantum") invariants of something are homotopy invariants.

Homotopy

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Definition

Let X, Y be a topological spaces, and I = [0, 1]. A homotopy is an arbitrary continuous map

$$F: X \times I \to Y$$

Homotopy

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A homotopy can be viewed as a one-parametric family of continuous maps

$$F_t = F|_{X \times t} : X \times t \to Y, \qquad t \in [0, 1].$$

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Then the maps F_0 and F_1 are called homotopic, and F is a homotopy between them.

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Two continuous maps $f, g : X \to Y$ are homotopic if there is a homotopy $F : X \times [0, 1] \to Y$ between them, i.e. $f = F_0$ and $g = F_1$.

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Exercises

1) Prove that the relation \simeq to be homotopic on the space C(X, Y) of continuous maps between topological spaces X and Y is an equivalence relation.

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1) Prove that the relation \simeq to be homotopic on the space C(X, Y) of continuous maps between topological spaces X and Y is an equivalence relation. Equivalence classes are denoted by [X, Y] and called homotopy classes of maps from X to Y.

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Exercises

1) Prove that the relation \simeq to be homotopic on the space C(X, Y) of continuous maps between topological spaces X and Y is an equivalence relation. Equivalence classes are denoted by [X, Y] and called homotopy classes of maps from X to Y.

2) Let $f, f': X \to Y$ and $g, g': Y \to Z$ be continuous maps. If $f \simeq f'$ and $g \simeq g'$ then $g \circ f \simeq g' \circ f': X \to Z$.

• The map $F : \mathbb{R} \times I \to \mathbb{R}$ given by

$$F(x,t) = t\cos(x) + 2^{t^2 - x^4} + \ln(x^2 + t^2 + 2)$$

is a homotopy.



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 More generally, let K be a convex subset of a topological vector space, p ∈ K be a point, and F : K × I → K be given by

$$F(x,t) = tx + (1-t)p$$

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A topological space X is contractible if the identity map id_X is homotopic to a constant map into some point. So there exists a continuous map $F: X \times [0,1] \to X$ such that $F_0 = id_X$ and $F_1(X) = z$ for some point $z \in X$.

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Theorem

Every convex subset of a topological vector space is contractible.

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Every convex subset of a topological vector space is contractible.

Not every topological space is contractible!

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Theorem

If Y is contractible if and only if for every topological space X any two continuous maps $f, g : X \to Y$ are homotopic.

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Exercise

Prove that every finite tree is contractible.

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A cone over X is the quotient $CX := X \times [0,1]/\{X \times 1\}$.

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Every contraction of X factors through the map into cone:



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A contraction of X can be regarded as a continuous map $F': CX \rightarrow X \times 0$ fixed on $X \times 0$.

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A contraction of X can be regarded as a continuous map $F' : CX \to X \times 0$ fixed on $X \times 0$. A subset $A \subset Y$ is a retract of Y if there exists a continuous map $r : Y \to A$ such that r(a) = a for all $a \in A$.

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Reformulation X is contractible whenever the base $X \times 0$ is a retract of CX.

Homeomorphism

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A continuous map $f: X \to Y$ is a homeomorphism if there exists a continuous map $g: Y \to X$ such that



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A continuous map $f: X \to Y$ is a homotopy equivalence if there exists a continuous map $g: Y \to X$ such that



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A continuous map $f: X \to Y$ is a homotopy equivalence if there exists a continuous map $g: Y \to X$ such that



Exercises

1) Homotopy equivalence is an equivalence relation.

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A continuous map $f: X \to Y$ is a homotopy equivalence if there exists a continuous map $g: Y \to X$ such that



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1) Homotopy equivalence is an equivalence relation.

2) A map homotopic to a homotopy equivalence is a homotopy equivalence as well.

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2) A map homotopic to a homotopy equivalence is a homotopy equivalence as well.

3) The set of self-homotopy equivalences $HE(X) \subset [X, X]$ of a topological space X constitute a subgroup in the semigroup [X, X].
Homotopy equivalence, 2

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Theorem

Let $F : X \to Y$ be a continuous map. Then the following conditions are equivalent:

- there exists a continuous map G : Y → X such that G ∘ F : X → X is homotopic to id_X (G is "right" homotopy inverse for F);
- (2) for any topological space Z the induced map

$$F^*: [Y, Z] \to [X, Z], \qquad F^*(g) = g \circ F: X \xrightarrow{F} Y \xrightarrow{g} Z$$

is a bijection.

Similarly, the following conditions are also equivalent:

- (1') there exists a continuous map G: Y → X such that F ∘ G': Y → Y is homotopic to id_Y (G' is a left" homotopy inverse for F);
- (2') for any topological space Z the induced map

$$F_*: [Z, X] \to [Z, Y], \qquad F_*(h) = F \circ h: Z \xrightarrow{h} X \xrightarrow{F} Y$$

is a bijection.

If both conditions (1) and (1') hold then G and G' are homotopic. In particular, $F : X \to Y$ is a homotopy equivalence iff F^* and F_* are bijections for all spaces Z.

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Exercise

For a topological space X TFAE:

() X is contractible (id_X is homotopic to a constant map)

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For a topological space X TFAE:

- **()** X is contractible (id_X is homotopic to a constant map)
- (i) $X \times 0$ is a retract of the cone CX

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Exercise

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- m any two maps $f,g:Y \to X$ are homotopic

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- (i) $X \times 0$ is a retract of the cone CX
- m any two maps f,g:Y o X are homotopic
- \mathbf{O} X is homotopy equivalent to a point

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Proof (i) \Leftrightarrow **(iv)**: Let $p_z : X \to \{z\}$ be a constant map.



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(i) means that $p_z \simeq id_X$ and this is the same as (iv).

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Let $A \subset X$ be a subset. A deformation of X into A is a homotopy $F : X \times I \to X$ such that

- $F_0 = \operatorname{id}_X$
- $F_t(A) \subset A$ for all $t \in I$
- $F_1(X) \subset A$.

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Theorem

Let $F : X \times I \to X$ be a deformation of X into A. Then the map $F_1 : X \to A$ is a homotopy equivalence.



Note that $F|_{A \times I} : A \times I \to A$ is a homotopy between $F_0|_A = id_A$ and $F_1|_A$.

Let $A \subset X$ be a subset. A deformation retraction of X on A is a homotopy $F : X \times I \to X$ such that

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We use the following notations:

- $X \nearrow Y$ for the inclusion $X \subset Y$, so it is an expansion
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Theorem (Chapman)

Let X and Y be two finite connected CW-complexes (polyhedrons). Then a map $f : X \to Y$ is a simple homotopy equivalence iff the map $f \times id : X \times Q \to Y \times Q$ is homotopic to a homeomorpism, where $Q = \prod_{i=1}^{\infty} [0,1]$ is a Hilbert cube.

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- ③ f̂(1) f̂(0) ∈ Z and this number does not depend on replacing f̂ with f̂_n.
- ⓐ The correspondence $f \mapsto f(1) f(0) \in \mathbb{Z}$ induces a bijection $[S^1, S^1] \cong \mathbb{Z}$.



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The set $\pi_0(X, x)$

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Exercise. Prove that the map $p: C((S^0, 0), (X, x)) \to X$ associating to each $f: (S^0, 0) \to (X, x)$ the value $f(1) \in X$ induces a bijection between $\pi_0(X, x)$ and the set of path components of X.

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Exercise. Let G be a topological group with unit e, and G_e be the path component of e in G. Prove that

- **1** G_e is a normal subgroup of G;
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Exercise. Let G be a topological semigroup. Prove that

- **1** Partition of G into path components $\xi = \{G_{\alpha}\}_{\alpha \in A}$ is a congruence, that is if $a, a' \in G_{\alpha}$ and $b, b' \in G_{\beta}$, then ab and a'b' belong to the same path component of G.
- 2) Hence the quotient set G/ξ which can be identified with $\pi_0(G,g)$ for any $g \in G$ is a semigroup, and the map $G \to \pi_0(G,g)$ is a semigroup homomorphism.

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Exercises

• Every continuous map $f : X \to Y$ induces a map $f_0 : \pi_0(X, x) \to \pi_0(Y, f(x))$ defined by $f_0[\alpha] = [f \circ \alpha]$, where $\alpha : (S^0, 0) \to (X, x)$.

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$$\alpha * \beta(t) = \begin{cases} \alpha(2t), & t \in [0, \frac{1}{2}], \\ \beta(2t-1), & t \in [\frac{1}{2}, 1]. \end{cases}$$

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Then the operations in $\pi_1(X, x)$ is defined by $[\alpha] * [\beta] = [\alpha * \beta]$. **Exercise**. 1) Prove that homotopy class of the constant map I into x is the unit of $\pi_1(X, x)$. 2) Prove that inverse to $[\alpha]$ is the homotopy class of the map $\beta : I \to X$ given by $\beta(t) = \alpha(1 - t)$.

Exercises.

1 $\pi_1(point) = 0.$



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• Every continuous map $f : X \to Y$ induces a map $f_1 : \pi_1(X, x) \to \pi_1(Y, f(x))$ defined by $f_1[\alpha] = [f \circ \alpha]$, where $\alpha : (S^1, *) \to (X, x)$.

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Higher homotopy group $\pi_k(X, x)$

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Let X be a topological space, $x \in X$, S^k be the circle and $* \in S^k$ be a point, and $k \ge 0$. Then k-th homotopy group of X at point x is the set of homotopy classes $[(S^k, *), (X, x)]$. It is denoted by $\pi_k(X, x)$, and these groups were introduced by W. Hurevicz.

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Theorem. $\pi_k(X, x)$, $k \ge 2$, has a structure of a group and that group is always abelian.

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Proof. Let $\alpha, \beta : (I^k, \partial I^k) \to (X, x)$ be two maps.

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Then the relative k-th homotopy group of the triple (X, A, x) is the set of homotopy classes

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- **2** Every continuous map $f: (X, A, x) \to (Y, B, y)$ induces a map $f_k: \pi_k(X, A, x) \to \pi_k(Y, B, f(x))$ defined by $f_k[\alpha] = [f \circ \alpha]$, where $\alpha: (I^k, \partial I^k, I_-^{k-1}), (X, A, x).$

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- **3** Let G be a topological group with unit e and H be its subgroup. Then $\pi_1(G, H, e)$ has a structure of a group. Moreover, the maps

$$\pi_1(G, e) \xrightarrow{j_1} \pi_1(G, H, e) \xrightarrow{\partial_1} \pi_0(H, e)$$

are group homomorphisms.

Long exact sequence of homotopy groups Let (X, A, x) be a triple, so $x \in A \subset X$.

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3 Let $\alpha : (I^k, \partial I^k, I^{k-1}_-), (X, A, x)$ be a representative of an element of $\pi_k(X, A, x)$. Then, in particular, $\alpha(I^{k-1}_+) \subset A$ and $\alpha(\partial I^{k-1}_+) = x$. Thus we get the restriction map $\alpha|_{I^{k-1}_+} : (I^{k-1}, \partial I^{k-1}) \to (A, x)$ being a representative of some element $\pi_{k-1}(A, x)$.

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Solution Let α : (I^k, ∂I^k, I^{k-1}_−), (X, A, x) be a representative of an element of π_k(X, A, x). Then, in particular, α(I^{k-1}₊) ⊂ A and α(∂I^{k-1}₊) = x. Thus we get the restriction map α|_{I^{k-1}₊} : (I^{k-1}, ∂I^{k-1}) → (A, x) being a representative of some element π_{k-1}(A, x). In fact, α ↦ α|_{I^{k-1}₊} induces a so called boundary homomorphism: $∂_k : π_k(X, A, x) → π_{k-1}(A, x)$

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Thus we get an infinite sequence of homomorphisms:

$$\cdots \xrightarrow{\partial_{k+1}} \pi_k(A, x) \xrightarrow{i_k} \pi_k(X, x) \xrightarrow{j_k} \pi_k(X, A, x) \xrightarrow{\partial_k}$$

$$\pi_{k-1}(A, x) \xrightarrow{i_{k-1}} \pi_{k-1}(X, x) \xrightarrow{j_{k-1}} \pi_{k-1}(X, A, x) \xrightarrow{\partial_{k-1}} \cdots$$

$$\cdots \xrightarrow{\partial_2} \pi_1(A, x) \xrightarrow{i_1} \pi_1(X, x) \xrightarrow{j_1} \pi_1(X, A, x) \xrightarrow{\partial_1}$$

$$\pi_0(A, x) \xrightarrow{i_0} \pi_0(X, x) \xrightarrow{\cong} \pi_0(X, A, x).$$

Theorem

The long sequence of homotopy groups for the triple (X, A, x) is exact.

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1 Compute homotopy groups $\pi_k(I, \partial I, 0)$.



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Homotopy



Homotopy Homotopy equivalence



Homotopy Homotopy equivalence Contractible space



Homotopy Homotopy equivalence Contractible space Retract

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Homotopy Homotopy equivalence Contractible space Retract Deformation onto subspace

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Homotopy Homotopy equivalence Contractible space Retract Deformation onto subspace Deformational retract

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